

CCM FAMILY Magnetic components for space applications Optimized for multi output Flyback transformers

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eesa



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SUMMARY

- Introduction : evolution of magnetic components in space Definition – How to satisfy it?
- Part 1 : Family qualification by ESA/CNES Why choose Technology Flow over QPL products? Qualification steps
- Part 2 : Performance characterization of CCM technology
 Thermal behavior
 Frequency response and Current saturation (standard CCM inductors)
- Part 3 : Optimization for multi output Flyback transformers
 The cross regulation problem or voltage deviations on some outputs
 PhD thesis definition Different stages of work Present and future results
- Conclusion

Components that meet present and future customer needs





ESA

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Discover

Chameleon Concept Magnetics



Chameleon Concept Magnetics | What is CCM?



echnolog

- a SMD component with **5 sizes available 6 soon (CCM30)**
- is done for Harsh environments and High reliability applications
- allows standard or custom **power inductors** Common/Differential Mode, Filtering, PFC chokes
- allows **custom design** of multi-outputs transformers Flyback, Forward, Push-Pull,... up to 200W (350W soon)









0.15

WHAT IS A CCM?



Pin section: 0.9 × 0.3 0.9 × 0.3 0.9 × 0.3 0.9 × 0.3 0.9 × 0.3 0.9 × 0.3 0.9 × 0.3 0.9 × 0.3 0.9 × 0.3 0.9 × 0.3 0.0 × 0.



CCM4 dimensions

EXXELIA

CCM25 dimensions

CCM family : INTRODUCTION

- What are the new technical needs and constraints for specific transformers?
- First : Applications with more outputs
 Need for more In/Out pins
 More different voltages and power levels
- Second : Increase in the power to volume and power to weight ratios We can no longer take large safety margins
 - ==> need to know **all the technical limitations** of the product Reliability, internal heating, frequency response, current saturation
- Third : Development time is getting shorter
 Breadboards/Prototypes must work the first time ==> design method must be accurate

Even specific products must avoid qualification time

==> have to be **already qualified before** BreadBoard/Prototype step

Part 1: ESA qualification

• CCM family : What is this, and what is it for?

Same technology for 5 shapes

Ferrite circuit around windings wound in a bobbin, cabled on a leadframe and moulded For both standard and custom components

Different types of functions : inductors (DMC, CMC), pulse/SMPS/measurement transformers

- ==> QPL qualification not adapted
- Technology Flow is better

• What is a Technology Flow?

Exxelia must prove that CCM technology is space compliant 1st step Evaluation (Exxelia), 2d step Qualification (ESA/CNES) Exxelia has to define : bill of materials

manufacturing process

design rules

and list of tests to be performed

Part 1: ESA qualification

• Bill of materials

3 key raw materials : Bobbin, leadframe and magnetic circuit Other materials : wires, solid insulation, glue/resin/varnish, weld, ink, package

• Manufacturing process

3 key steps : winding, cabling, moulding Other steps : gluing, assembling, marking, testing, packaging

• Design rules

all theoretic actions the designer has to do upstream to prevent surprises downstream

Test campaigns

All those in Charts F4 SG1, SG2 and SG3

Thermal shocks, Temperature rise, Overload, Soldering heat, Vibrations, Mechanical shocks Operating life, Permanence of marking, Solderability, Terminal strength, Dielectric, Moisture

Part 1: ESA qualification

3/3

- Summary of work carried out
 - More than 100 components designed, manufactured, and tested many configurations of functions / shapes / tests
 - Some components destroyed to identify safety margins on thermal, mechanical, dielectric aspects
 - Evaluation took several years to complete

Result : Qualification was successful on first try

Conclusion

Respecting BOM, process and design rules qualified

Exxelia has the right to offer any function in CCM shapes without any mandatory testing for customer



Part 2 : CCM technology performances 1/7

- Security margins must be reduced
- Ok, but to get close to the limits, you have to know them!
 Maximum permissible loss value → leads to internal heating (Tmax < 125°C)</p>
 Maximum operating frequency → above resonant frequency component is no more inductive
 Saturation curve → which inductor value at which excitation current?
- How can these characteristics be determined?
 - analytic calculations, software simulations, experimental measurements? We decided to carry out 3 experimental campaigns :
 - 1 Thermal resistance determination for each of 5 shapes
 - 2 Inductance versus frequency curves for standard inductors
 - 3 Inductance versus current curves for standard inductors



Part 2 : CCM technology performances 2/7

- Thermal resistance Rth of CCM4, CCM5, CCM6, CCM20 and CCM25
- Definition of test conditions
 Use of inductors with one winding
 connected to all pins one side
 Measurements in vacuum are very complex
 ==> in natural convection in the air first
 Copper losses (heating source) only

==> DC current excitation / measurement of Rwind Component on PCB / all pins soldered

/ no glue / no copper except for large current paths
 Component in a (pierced) box inside a ventilated oven
 / temperature controlled

Measurement bench



Part 2 : CCM technology performances 3/7

Measurements realised for each of 5 shapes

2 L values / 5 Tenv : 25, 50, 75, 100, 125 and 150°C / up to 15 meas. points for each Tenv



• Complements and further work

Results applied for all CCM components / We have a math model air convection → vacuum 3D simulations in progress to validate these curves ... 1st results are promising Measurements in vacuum are planned

Part 2 : CCM technology performances 4/7

- Frequency behavior for CCM4, CCM5, CCM6, CCM20 and CCM25 standard inductors
- Definition of test conditions
 Use of inductors with one winding
 connected to all pins one side
 Constant excitation, between 100µT and 1mT
 Components soldered on a brass plate
 RLC meter calibrated after 1 hour functioning

Measurement device





Part 2 : CCM technology performances 5/7

• Measurements realised for each of 5 shapes

2 L values / up to 15 meas. points for each inductor value



• Result overview

Majority of inductors are usable at least up to 1MHz

All of inductors are usable at least up to 400kHz

Part 2 : CCM technology performances 6/7

α=0,5

- Saturation behavior for CCM4/5/6/20/25 standard inductors
- Definition of test conditions
 Use of inductors with one winding
 connected to all pins one side
 180° phase shift full bridge DC supply
 DC + AC (200kHz) excitation with duty or

DC+AC (300kHz) excitation with duty cycle > 0,5

 ΔI constant as long as no saturation

Period nb controlled to achieve desired DC current

L value measured with

current rise slope

Without saturation







α=0.75



Part 2 : CCM technology performances 7/7

• Measurements realised for each of 5 shapes

2 L values / 2 Tenv, ambiant and 125° C / up to 15 meas. points for each Tenv 2 types of curves L function of Idc or Imax (Idc+ Δ I/2)



• Result overview

Big ≠ between 25 and 125°C : taking account of thermal behavior of Ferrite is mandatory Main interest : to detect the beginning of saturation

Part 3: multi Flyback optimization 1/4

- What are voltage deviations also named cross regulation problem?

 At nominal point of load, some output voltages are different from theoretical values
 If power level at regulated output varies, some non regulated output voltages values vary
 Current waveform on some auxiliary outputs is very different from theoretical triangle shape
- Observation :

The more different output / voltage levels / power levels ...

... The greater the probability to have voltage deviations On which output(s) : ???

Of which value : ??? some % up to x2!

Actual solution : linear regulators

==> more volume/weight, less efficiency, more heating

Aim : Is it possible to remove (some!) linear regulators?



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Part 3 : multi Flyback optimization

Charge : Transformer is mostly responsible

Is the customer able to define a technical constraint to respect for the supplier? **No** Problem seriousness depends on application and even on piece inside a manufacturing batch Magnetic root cause (transformer), but power electronics consequence (converter)

- ==> need to work in **both electromagnetism and power electronics**
- EXXELIA decided to manage a PhD thesis on this subject

Aims :

1 Understand scientific problem, Identify root causes (transformer, other components?),

2 Find solutions, Take account of voltage deviations in design and manufacturing process

Partners : G2Elab laboratory, D. Motte Michellon student, CNES, Steel Electronique









Part 3: multi Flyback optimization

- 3/4
- PhD step 1 : Understanding the scientific problem, identify root causes
 Study of magnetic behavior of several transformers
 ==> use of FLUX finite element simulation software
 Identification of a circuit model compliant with several softwares (Psim, Spice, other)
 ==> extended Cantilever magnetostatic model
 Calculation of all output voltages for different transformers/converters
 ==> use of Psim circuit software

• Result of analysis :

75% of the problem comes from the transformer : magnetic coupling between all secondaries 25% of the problem comes from drawbacks of some other components of the converter

• Actions :

creating an analytical model to take account of leakage inductances between secondaries
 use this model to quickly calculate all output voltages

Part 3 : multi Flyback optimization

 PhD step 2 : Finding theoretical and industrial solutions
 We identified relationship between CCM winding process, couplings between secondaries and voltage deviations

We identified which other components and which drawbacks are concerned

For the moment, one method of winding CCM to avoid worst cases of voltage deviations and to minimize variations from one piece to another

applied since 01/01/2022 for all designed Flyback in CCM

In progress a software to optimize (minimize) voltage deviations and to identify best cases of CCM winding processes

Increase of know-how for the customers' benefit

CCM family : CONCLUSION

• Whatever the function you need

Component is already qualified ==> Reliability / Security / Money saving Many pins ==> many input/output possibilities You know its thermal behavior ==> have a good idear of its energy/power limit

• For inductor applications

You can have standard or custom components You know frequency and current saturation responses

• For multi output Flyback transformers

Design method focused on1 meeting customer's need as close as possible2 volume and weight reductions

==> CCM technology is well adapted for space ... and we continue to improve it Thank you for your attention

Questions?



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